



Bridgeland Stability of Line Bundles on Smooth Projective Surfaces

Daniele Arcara

daniele.arcara@email.stvincent.edu

Eric Miles

miles@math.colostate.edu



Overview

Idea

A **Bridgeland Stability Condition (BSC)** on a smooth projective variety X assigns the label of **(semi)stable** or **unstable** to each complex $E \in D^b(\text{Coh } X) =: D(X)$ in a meaningful way.

Question

When is \mathcal{O}_S given the label semistable in a certain class of “divisorial” BSCs defined on surfaces? (this will characterize the stability of all line bundles)

Theorem 1

If the surface S has no curves C satisfying $C^2 < 0$, then \mathcal{O}_S is σ -stable for all $\sigma \in \text{Stab}_{\text{div}}(S)$

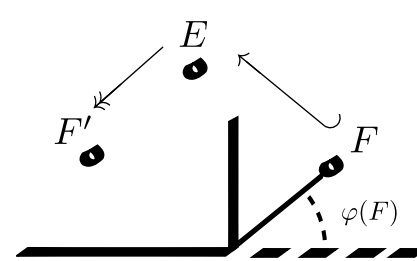
Bridgeland Stability Conditions

General Setup

Let S be a smooth projective surface. A **stability condition** σ is a pair $\sigma = (Z, \mathcal{A})$ where...

- \mathcal{A} is a *heart* of $D(S)$
- $Z : K_{\text{num}}(S) \rightarrow \mathbb{C}$ is a group homomorphism satisfying three properties:

1 (Positivity) for all $0 \neq E \in \mathcal{A}$, have $Z(E) \in \{re^{i\pi} \mid r > 0, 0 < \varphi \leq 1\}$.



We say $E \in \mathcal{A}$ is σ -(semi)stable if for all nontrivial $F \hookrightarrow E$ in \mathcal{A} we have $\varphi(E) > (\geq) \varphi(F)$.

2 (HN-Filtrations) objects $E \in \mathcal{A}$ have well-behaved filtrations in terms of σ -semistable objects

3 (Support Property) images of object classes via Z do not accumulate at the origin

$\text{Stab}(X) = \{\text{all BSCs on } X\}$ is a complex manifold [3].

Divisorial BSCs

By [2], a choice of ample \mathbb{R} -divisor H and general \mathbb{R} -divisor D give a BSC $\sigma_{D,H}$ where

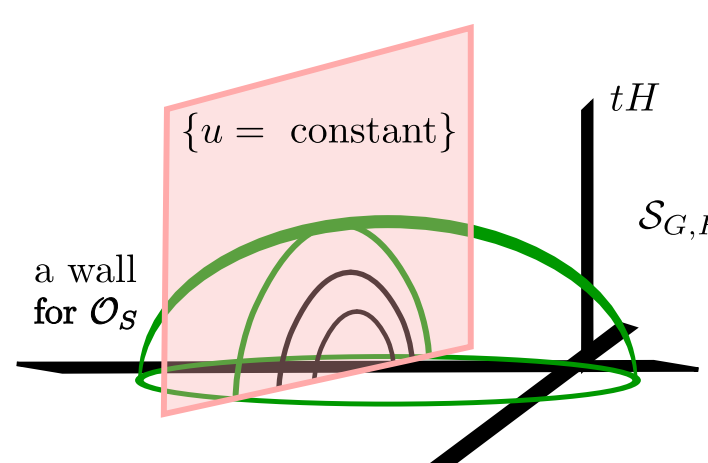
- $\mathcal{A}_{D,H}$ is the tilt of $\text{Coh } X$ at the Mumford H -slope $D.H$
- $Z_{D,H}(E) = -\int e^{-(D+iH)} \text{ch}(E)$

We denote the set of all such BSCs by $\text{Stab}_{\text{div}}(S)$.

Walls in $\text{Stab}_{\text{div}}(S)$

Slices of $\text{Stab}_{\text{div}}(S)$

A choice of ample divisor H and divisor G such that $H.G = 0$ give us a 3-space $\mathcal{S}_{G,H} \subset \text{Stab}_{\text{div}}(S)$ containing the stability conditions $\sigma_{D,A}$ where $D = sH + uG$ and $A = tH$ for $s, u \in \mathbb{R}$ and $t > 0$.



- In $\mathcal{S}_{G,H}$, the **walls** for \mathcal{O}_S (i.e. the set of BSCs σ with some $E \hookrightarrow \mathcal{O}_S$ and $\varphi(E) = \varphi(\mathcal{O}_S)$) are quadric surfaces

- inside the planes $\{u = \text{constant}\}$, the walls for \mathcal{O}_S are nested [4], so we may consider just the $t = 0$ -plane to understand the position of walls for \mathcal{O}_S .

When does $E \hookrightarrow \mathcal{O}_S$?

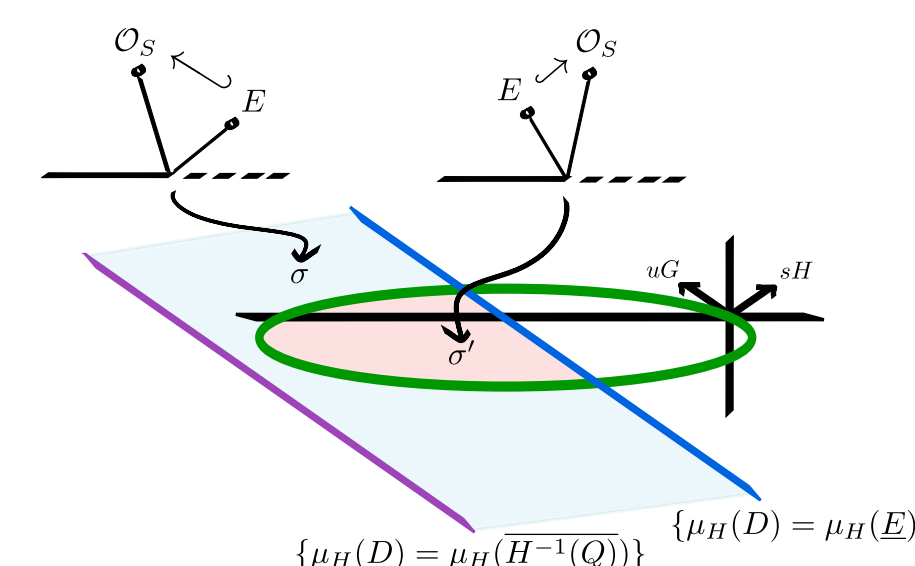
- $E \hookrightarrow \mathcal{O}_S$ in $\mathcal{A}_{D,H}$ implies E is a sheaf, but $Q := \text{coker}(E \hookrightarrow \mathcal{O}_S)$ may be a two-term complex $Q = Q_{-1} \rightarrow Q_0$.

There is a HN-filtration of Mumford H -semistable sheaves for both E and $H^{-1}(Q)$.

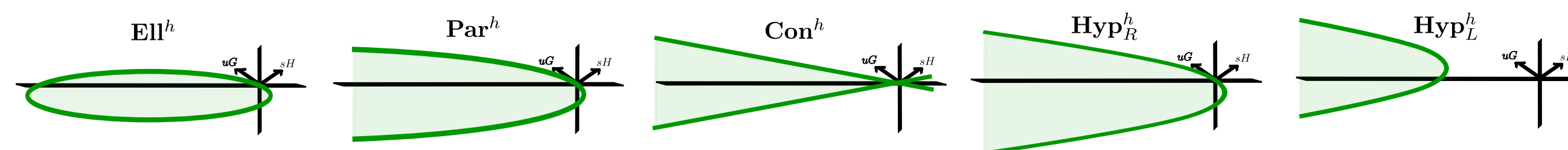
- For $E \hookrightarrow \mathcal{O}_S$ at $\sigma_{D,tH}$, we require...

$$\mu_H(\overline{H^{-1}(Q)}) \leq \mu_H(D) < \mu_H(\underline{E})$$

- where μ_H denotes the Mumford H -slope
- $\overline{H^{-1}(Q)}$ and \underline{E} denote respectively the Mumford H -semistable factor of $H^{-1}(Q)$ (of E) with the largest (smallest) H -slope



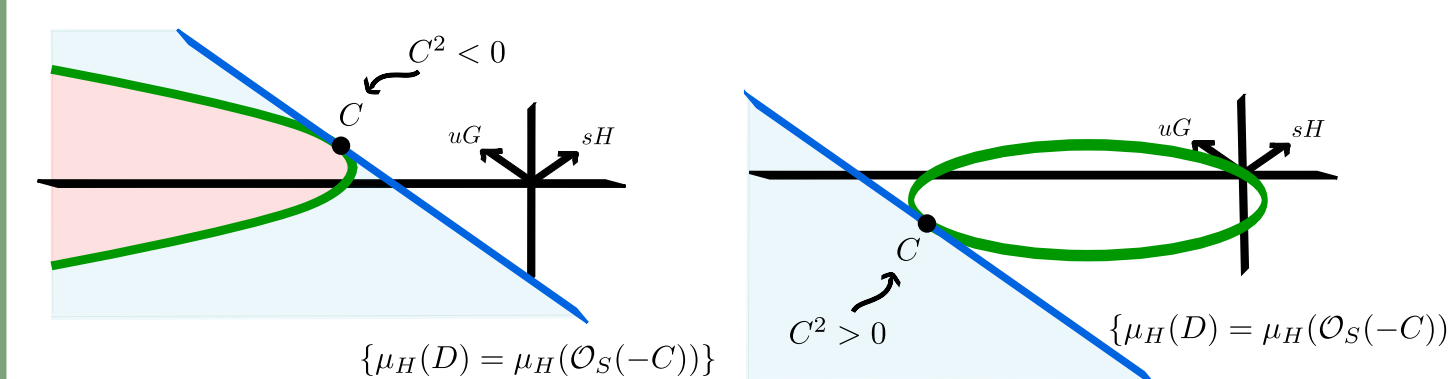
Wall Types for \mathcal{O}_S in $t = 0$ -plane



Tools for Proof

Rank 1 Case

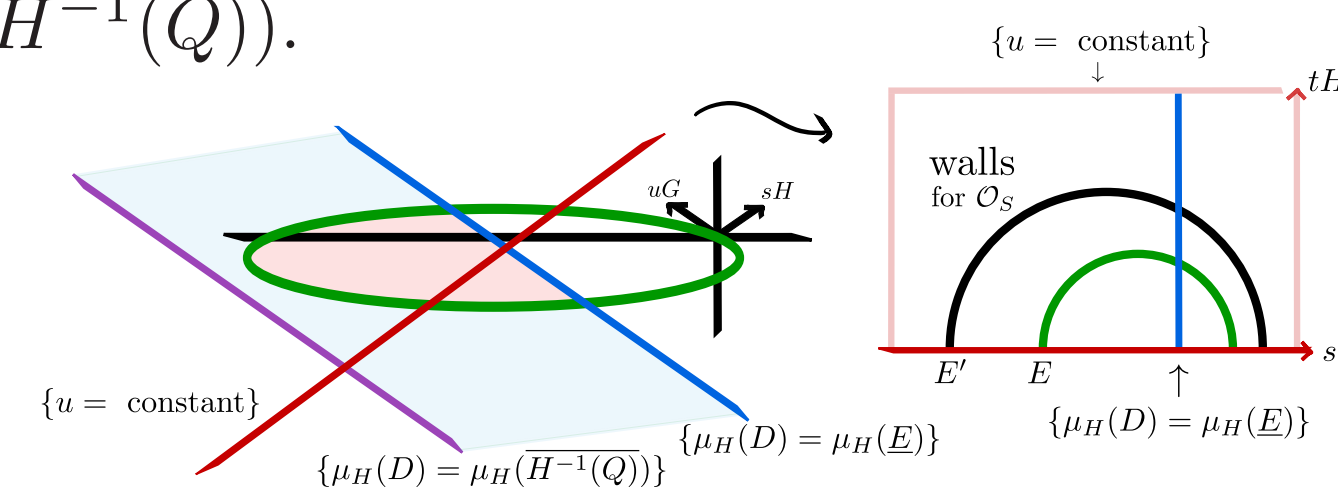
Let C be the class of a curve. The wall for $\mathcal{O}_S(-C) \hookrightarrow \mathcal{O}_S$ is determined by the point in the $t = 0$ -plane corresponding to C .



The above pictures show that $\mathcal{O}_S(-C) \hookrightarrow \mathcal{O}_S$ and $\varphi(\mathcal{O}_S(-C)) \geq \varphi(\mathcal{O}_S)$ implies that $C^2 < 0$, i.e. that C is a **negative curve**.

Bertram's Lemma

In [1] it is shown that in a plane $\{u = \text{constant}\}$ where the wall for $E \hookrightarrow \mathcal{O}_S$ intersects the line $\{\mu_H(D) = \mu_H(\underline{E})\}$ or the line $\{\mu_H(D) = \mu_H(\overline{H^{-1}(Q)})\}$, there is a wall above the one for E which is obtained by omitting \underline{E} (respectively $\overline{H^{-1}(Q)}$) from the Mumford H -filtration of E (respectively $H^{-1}(Q)$).

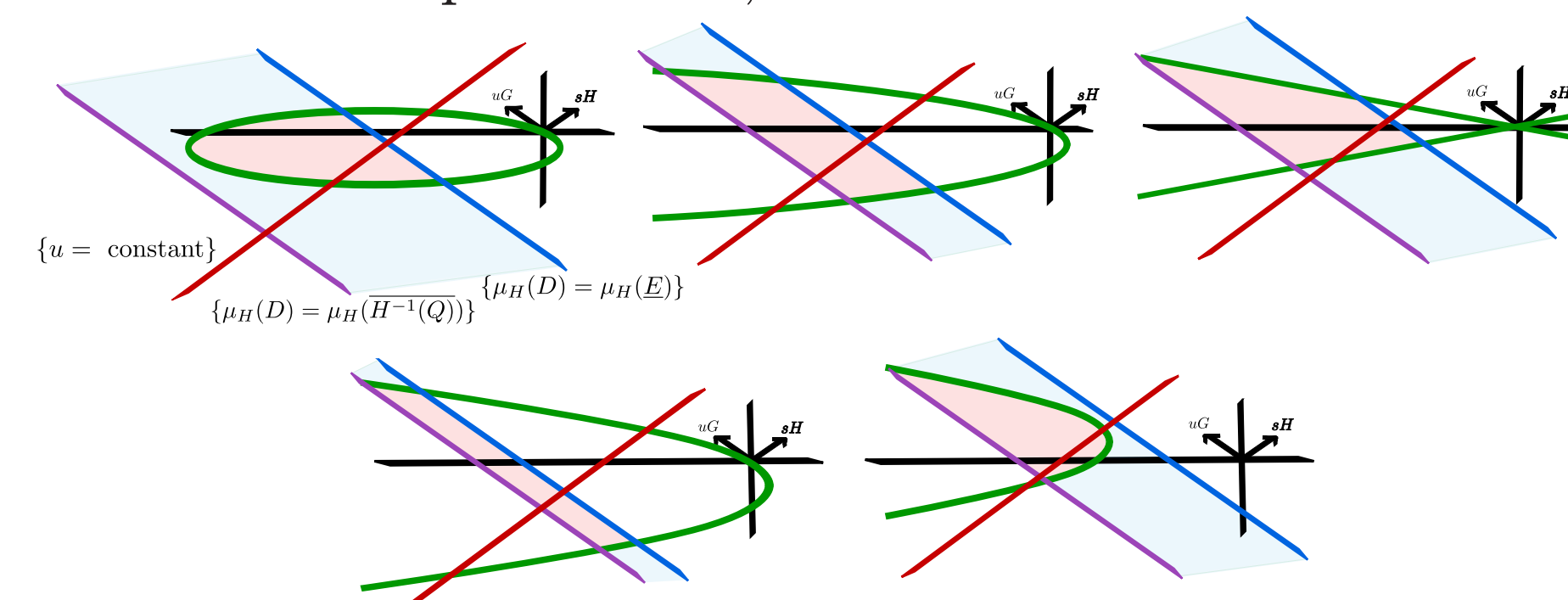


Sketch of Proof of Theorem 1

The proof is by contradiction via minimal counterexample.

Since S has no curves C satisfying $C^2 < 0$, the Rank 1 Case shows that no rank 1 E can destabilize \mathcal{O}_S . Now, suppose that at some σ there is an E with rank at least 2 satisfying $E \hookrightarrow \mathcal{O}_S$ and $\varphi(E) \geq \varphi(\mathcal{O}_S)$. We may suppose that no E' of lower rank satisfies this.

But, if we consider the wall types possible for $E \hookrightarrow \mathcal{O}_S$, we see one can always find a u such that Bertram's Lemma gives us an E' of lower rank than E which satisfies $E' \hookrightarrow \mathcal{O}_S$ and $\varphi(E') \geq \varphi(\mathcal{O}_S)$ at some σ' (see figure). This contradicts our assumption on E , and we are done.



Other Work

Theorem 2

If S has Picard rank 2 and has one irreducible negative curve C , then \mathcal{O}_S is destabilized only by $\mathcal{O}_S(-C)$.

Future Work & Interests:

- S with Picard rank ≥ 2 , general case
- Quiver regions for Del Pezzo surfaces
- Stability and birational geometry for 0-dim'l ideal sheaves

References

- [1] D. Arcara, A. Bertram, I. Coskun, and J. Huizenga. “The Minimal Model Program for the Hilbert Scheme of Points on \mathbb{P}^2 and Bridgeland Stability”. *Adv. Math.*, 235:580-626, 2013.
- [2] D. Arcara and A. Bertram. “Bridgeland-Stable Moduli Spaces for K-Trivial Surfaces”. *JEMS*, 15(1):1-38, 2013. (appendix by Max Lieblich).
- [3] T. Bridgeland. “Stability Conditions on Triangulated Categories”. *Ann. Math.*, 166:317-345, 2007.
- [4] A. Maciocia. “Computing the Walls Associated to Bridgeland Stability Conditions on Projective Surfaces”. <http://arxiv.org/abs/1202.4587>